

AN INTEGRATED HIGH-PERFORMANCE COMPUTING RELIABILITY PREDICTION FRAMEWORK FOR GROUND VEHICLE DESIGN EVALUATION

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An Integrated HPC Reliability Prediction Framework



- Presentation Scope:
 - To present on overview of an integrated HPC stochastic physics-based framework that has been developed for vehicle reliability prediction.
 - Illustrative application to the HMMWV military system
 - Focus on:
 - The front-left suspension system (FLSS)
 - Qualitative aspects and methodology, not precise quantitative results







Vehicle Reliability Prediction Process



VEHICLE RELIABILITY PREDICTION MULTISTEP PROCESS





Vehicle Reliability Prediction. Implementation



VEHICLE RELIABILITY IMPLEMENTATION CHART





Stochastic Road Surfaces



High Spatial Transverse Correlation

Low Spatial Transverse Correlation





Simulated vs. Measured Road Profiles



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Stochastic Road Surfaces









Vehicle Behavior to Stochastic Road Surfaces







Flat road with no topography Effects; Passing a Random Bump

Using HMMWV ADAMS Model







With topography Effects; Smooth and Rough Stochastic Roads





Vehicle Behavior to Stochastic Road Profiles



Effects of Road Topography on FLSS UCA Ball Joint Forces





Stochastic Vehicle Behavior



- Stochastic Vehicle Suspension Parameters:
 - All four wheel suspensions
 - Only front-wheel suspension

For a wheel suspension, 13 stochastic parameters are considered. For all four wheel suspensions there are 52 stochastic parameters. For each road and speed scenarios, 40 simulations were performed using LHS.

For practicality, we condensed the 52 stochastic parameters in 4 stochastic variation features:

- UCA Bushings (4 variables = 2 stiffness and 2 damping parameters)
- LCA Bushings (4 variables = 2 stiffness and 2 damping parameters)
- Tire (3 variables = lateral, tangential and radial stiffness parameters)
- Spring/Absorber (2 variables = 1 stiffness and 1 damping parameters)





Stochastic Vehicle Behavior



GVSETS

Stochastic Parameters of the ADAMS HMMWV Suspension System (FLSS)

SPRING-SHOCK												
ABSORBER		TIRE			BUSHING UCA				BUSHING LCA			
STIFF	DAMP	PAR 1	PAR 2	PAR 3	STIFF 1	STIFF 2	DAMP 1	DAMP 2	STIFF 1	STIFF 2	DAMP 1	DAMP 2
LN(1,0.025)	LN(1,0.05)	LN(1,0.025)	LN(1,0.05)	LN(1,0.1)	LN(1,0.025)	LN(1,0.025)	LN(1,0.05)	LN(1,0.05)	LN(1,0.025)	LN(1,0.025)	LN(1,0.05)	LN(1,0.05)
0.9976	0.9407	1.0357	1.0012	1.0755	0.9016	1.0404	1.0209	1.0045	0.9355	0.9431	0.9465	0.9521
1.0000	1.0047	1.0236	0.9054	0.9975	0.8877	1.0772	1.0671	1.0779	1.0350	1.0314	0.9781	0.8573
0.9921	0.9969	0.9629	0.9171	1.0355	0.9529	1.0299	1.0004	0.9967	0.9800	1.0358	1.0127	0.9054
0.9911	0.9780	1.0711	0.9187	0.9763	0.9560	0.9401	1.1562	0.9853	0.9919	0.9515	0.9387	1.0172
0.9722	1.0008	0.9673	0.9950	1.0029	1.0778	1.1147	0.9273	0.9714	0.9806	1.0154	0.9730	0.9283
1.0231	0.9702	0.9905	0.9823	0.8934	1.0084	1.0501	0.9892	0.9683	0.9536	0.8863	0.9773	1.0970
1.0362	1.0253	0.9304	0.9994	0.9560	1.0677	0.9681	1.0395	1.0646	1.0091	1.0681	1.0766	0.9827
1.0209	0.9917	1.0650	0.9898	1.0016	0.9760	1.0340	1.0686	1.0348	1.1950	0.9364	1.0243	0.9257
0.9810	0.9405	1.0696	1.0506	1.0681	0.9595	0.9632	0.9803	1.0290	1.0055	1.0222	1.0086	1.0530
1.0256	0.9739	0.8864	0.9909	0.9621	1.0090	1.0215	1.0961	1.0269	1.0606	0.9667	1.0385	1.0190

Effects of Stochastic Vehicle Behavior on the FLSS Fatigue Damage

Simulation Sets	Node=2275	Node=4800	Node=5406
(Each of 10 Simulations)	Mean/Std	Mean/Std	Mean/ Std.
High_Roughness_Straight_30MPH_set1	1.347724e-003	1.555955e-005	6.960761e-005
	(3.951257e-005)	(7.893527e-007)	(1.848916e-006)
High_Roughness_Straight_30MPH_set2	1.331116e-003	1.643080e-005	6.597428e-005
	(2.192678e-005)	(6.492225e-007)	(2.088339e-006)
High_Roughness_Straight_30MPH_set3	1.222983e-003	1.456184e-005	5.178260e-005
	(6.239249e-005)	(2.017415e-007)	(4.434275e-006)
High_Roughness_Straight_30MPH_set4	1.241959e-003	1.475359e-005	6.202625e-005
	(3.578063e-005)	(3.529030e-007)	(3.763194e-000)





Uncertainty in Stochastic Vehicle Predicted Behavior Due to FE Modeling Errors



36K dofs model

Load Case – Bushing 2, Z Load

Significant variations (up to 50%) in local stresses due to:

- FE Mesh Refinement
- Shell Element Type





96K dofs model



GVSETS

FE Modeling Uncertainties



Stochastic FEA for Stress Computation



Stochastic PARallel Tool for Analysis of Computational Unstructured-Mesh Solids (SPARTACUS). Applicable to Large-Size FE Models.





Stochastic FEA HPC Implementation for Local Stress Computation



Stochastic FEA HPC Strategy in SPARTACUS





Stochastic FEA HPC Implementation for Local Stress Computation



ParMETIS Partitioning for Stochastic Domain Decomposition

Dome Model











Engine Bladed-Disk Model

LCA Model









Ex Boll Joint Model, Dait X L. Learn about coupling!







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Stochastic FEA HPC Implementation for Local Stress Computation



TESTING AND VALIDATION

MODELING AND SIMULATION





Stochastic Response Surface Modeling for Stress Computation



10 D Stochastic Surface Using High-Order Stochastic Field Models







Front-Left Suspension System (FLSS) Models



FLSS ADAMS RBD Model and SPARTACUS FE Model

(36 Joint Component Forces/Moments Considered for FLSS)

ADAMS Model

SPARTACUS Model









Sensitivity Studies: Effects of Road Surface Variation Non-Gaussianity



High roughness segment, with given PSD, for an average vehicle speed 30mph

Simulated Road Profiles

LCA Busing Moment History

LCA Bushing Moment PDF





Progressive Damage Modeling for Interactive Mechanisms; HFC, LCF, Corrosion



Interactive Fatigue Damage Mechanisms for Vehicle on Rough Terrain





Sensitivity Studies: Effects of Damage Mechanism Model on Life Predictions

MSTV MODELING AND SIMULATION, TESTING AND VALIDATION

Predicted FLSS Life Using LDR and DCA Damage Models









⁰40



Life





Effects of Limited FEA Simulations on Life Predictions. Weibull vs. Lognormal Models.



Effect of Lack of Data (280 Simulations) on FLSS Life for Given Reliability







Summary/Concluding Remarks

MODELING RND SIMULATION, TESTING RND VALIDATION

An integrated HPC stochastic simulation framework has been implemented and demonstrated.

The integrated HPC reliability prediction framework incorporates the following constitutive parts:

- i) simulation of the stochastic operational environment,
- ii) stochastic vehicle multi-body dynamics analysis,
- iii) stress prediction in subsystems and components,
- iv) stochastic progressive damage analysis, and
- v) component life prediction including uncertainty from maintenance
- vi) reliability prediction at the component and the system levels.

Note:

Accurate stochastic modeling of road surface and topography is an important aspect of an overall vehicle reliability analysis. The non-Gaussian variations of the road profiles have a significant impact on the predicted vehicle fatigue reliability. These non-Gaussian variation aspects are often ignored.



