# NONLINEAR SEISMIC SSI FOR REINFORCED CONCRETE BUILDINGS IN ACCORDANCE WITH ENGINEERING BEST PRACTICES IN US AND JAPAN

### PART 1: Modeling of RC Structural Wall Nonlinear Behavior



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#### **DOE/NRC Natural Phenomena Hazards Meeting**

#### October 20-22, 2020

# **Purpose of This Presentation**

To describe the implementation of an efficient and practical nonlinear seismic SSI approach for the reinforced concrete shearwall NPP structures based on the best engineering design practices in US and Japan.

The idea behind the developed nonlinear SSI analysis tool (ACS SASSI Option NON) is to provide the needed practical support to engineering designers by providing a analysis tool which *in compliance with the current structural design standards and nuclear regulatory requirements*.

#### Acknowledgements:

We thank very much to the SHIMIZU structural designers who have closely cooperated with us over the last couple of years during the development of this nonlinear SSI tool, so that the newly produced Option NON software is compliant with the nuclear seismic design regulations in Japan.

# **Part 1 Presentation Content**

- 1. Brief Description of the Nonlinear SSI Methodology
- 2. Modeling RC Wall Nonlinear Behavior; Back-Bone Curves and Hysteretic Models
- 3. Modeling of Interaction Between Shear and Bending Effects
- 4. Comparative Nonlinear Results vs. PERFORM3D for A Low-Rise Shearwall Building
- 5. Comparative Nonlinear Results Vs. OpenSees Codes for A *Mid-Rise* Shearwall Building Continue in Part 2...

# 1. Brief Description of the Nonlinear SSI Methodology

The nonlinear SSI analysis is based on an iterative scheme that includes two separate computational steps at each iteration, as follows:

- <u>Step 1</u>: Perform an *equivalent-linear SSI analysis* in complex frequency via SASSI approach to compute the structural displacements for each nonlinear RC wall, and then,
- <u>Step 2</u>: Perform a *nonlinear time-integration analysis* for each RC wall submodel loaded with the SSI displacements from Step 1, to compute the in-plane shear and bending nonlinear wall responses using *standard-based BBCs and selected hysteretic models*. Then, determine *the equivalent-linear stiffness and damping for each wall* using DRF to be used for next SSI iteration, until converged.

#### REMARKS:

- 1) <u>Step 1</u> uses the *original, refined FE SSI model*, while <u>Step 2</u> uses a *reduced-order structural model* composed by nonlinear RC walls. Therefore, the nonlinear time-domain Step 2 analysis is extremely fast. For DES, *condensed soil impedance matrix* should be used for SSI iterations (ANALYS option).
- 2) This methodology was validated for several shearwall building models against CSI PERFORM3D code and the OpenSees 3D FIBER model and 2D MVLEM software.

# **Iterative Equivalent Linearization Using Variable or Constant DRF**

The *PSD-based DRF* is computed based on the frequency content of the PSD frequency computed for the nonlinear shear force or bending moment for each wall at each floor level and each iteration.

The DRF is computed based the PSD dominant frequency shifts at each iteration, as shown in the right-side figure.



# Hysteretic Responses for PSD-based Variable DRF vs. 0.80 DRF



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# Nonlinear ISRS Computed Using PSD-based DRF vs. 0.80 DRF

![](_page_6_Figure_1.jpeg)

# Main Steps of Nonlinear SSI Analysis Procedure Based on Engineering Best Practice Recommendations

Here are the main steps of the procedure:

- 1. Prepare structure FE model.
- 2. Select from structure FE model the nonlinear wall FE submodels
- 3. Perform initial SSI analysis for the gravity and seismic loads
- 4. Perform automatic wall cross-section geometry identification and automatic section cuts for each wall at each floor level for the gravity and seismic loads.
- 5. Compute shear and bending BBCs for each wall *per applicable best-practice recommendations*
- 6. Select shear and bending hysteretic wall models *per applicable best-practice recommendations*
- 7. Perform iterative nonlinear SSI analysis using the shear and bending hysteretic wall models and combine their responses at each iteration.
- 8. Post-process the final SSI results for the converged nonlinear response

# 2. Modeling RC Wall Nonlinear Behavior; Back-Bone Curves (BBC) and Hysteretic Models

**BBC Curves:** Are trilinear BBCs for both the shear and bending deformation following typical engineering practice, also recommended by the JEAC 4601-2015 Sect.3.5.6 (See figure below)

![](_page_8_Figure_2.jpeg)

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# Shear BBCs Computed per JEAC 4016-2015 Standard App.3.6

![](_page_9_Figure_1.jpeg)

# Shear BBCs Computed Based on ASCE 4 & ACI 318 Standards

### ACI 318-14 Section 18 for Shear Strength

$$V_n = A_{cv}(\alpha_c \lambda_{\sqrt{f_c'}} + \rho_t f_y)$$

where the coefficient  $\alpha_c$  is 3.0 for  $h_w / \ell_w \le 1.5$ , is 2.0 for  $h_w / \ell_w \ge 2.0$ , and varies linearly between 3.0 and 2.0 for  $h_w / \ell_w$  between 1.5 and 2.0. any one of the individual wall piers,  $V_n$  shall not be taken larger than  $10A_{cw} \sqrt{f_c'}$ , where  $A_{cw}$  is the area of concrete section of the individual pier considered.

#### **Option NON BBC\_GENERATION Module Implementation**

$$V = \left( \alpha_{e} \sqrt{f_{e}'} + \rho_{H} f_{y} \right) A_{W} \le 10 \sqrt{f_{e}'} A_{W}$$

### ASCE 4-16 Section 3

RC wall shear cracking occurs when the shear stress is larger than  $3.\sqrt{f_{'e}}$ 

### **Trilinear Shear BBC Curve**

![](_page_10_Figure_9.jpeg)

Does no depend

on axial force or

bending effects!

# **Computed Shear BBCs for TB RC Walls in Y-Dir**

![](_page_11_Figure_1.jpeg)

# **Computed Bending BBCs for TB RC Walls in Y-Dir**

![](_page_12_Figure_1.jpeg)

# **Hysteretic Models Library Available for Nonlinear RC Walls**

The hysteretic model library includes 8 types of models applicable to the structure RC walls:

- 1-Cheng-Mertz Shear (CMS)
- 2-Cheng-Mertz Bending (CMB)
- 3-Takeda (TAK)
- 4-General Massing Rule (GMR)
- 5-Maximum Point-Oriented (PO) for Shear per JEAC 4601 App. 3.6

6-Maximum Point-Oriented Degrading Trilinear (PODT) for Bending - per JEAC 4601 App. 3.6 7-Hybrid Shear (HYS) – obtained by combining PO Shear and CMS models 8-Hybrid Bending (HYB) - obtained by combining PODT Bending and CMB models

# **Cheng-Mertz Shear Hysteretic Model Against HU Wall Test Data**

### Cheng-Mertz Shear Model (Model 1)

![](_page_14_Figure_2.jpeg)

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# JEAC 4601 Point-Oriented (PO) Shear Model (Model 5)

![](_page_15_Figure_1.jpeg)

# Hybrid Shear Hysteretic Model Against HU Wall Test Data

Hybrid Shear Model (Model 7)

![](_page_16_Figure_2.jpeg)

![](_page_17_Figure_0.jpeg)

# Remarks for JEAC 4601 Point-Oriented-Degraded-Trilinear (PODT) Bending Hysteretic Model

![](_page_18_Figure_1.jpeg)

Hysteretic Damping varies from 0% to 15%; 0% at yielding and 15% at failure (ultimate).

![](_page_18_Figure_3.jpeg)

The low hysteretic damping values recommended in the JEAC 4601 are based on a series of experimental tests done for various shearwall configurations and typical NPP structure RC walls with larger thicknesses and reinforcement percentages than those of the RC walls in conventional structures (Taitokui report, 1987). These damping values are lower than those computed using FEA codes.

# Comparisons of JEAC and Cheng-Mertz Model Loops Based on Separate Nonlinear SSI Analyses (with Dynamic Effects)

![](_page_19_Figure_1.jpeg)

# 3. Modeling of Interaction Between Shear and Bending Effects

These interaction effects are included at each SSI iteration by the following Option NON options:

- 1) <u>Shear Governing</u>: Assuming that the shear stiffness variations are governing the wall stiffness degradation at each SSI iteration (RC wall material stiffness degradation based on the Shear hysteretic models only, i.e. material Esb=Es, fully coupled)
- 2) <u>Bending Governing</u>: Assuming that the bending stiffness variations are governing the wall stiffness at each SSI iteration (*RC wall material stiffness degradation based on the Bending hysteretic models only, i.e. material Esb=Eb, fully coupled*)
- 3) <u>Shear and Bending</u>: The equivalent bending and shear stiffnesses are computed independently at each SSI iteration (*RC wall material stiffness degradation based on both Shear and Bending hysteretic models, i.e. material Esb is different from Es and Eb*). An elliptical interaction curve for combining the shear and bending stiffnesses is applied at each SSI iteration.

# Computed AB ISRS for 0.70g: 1) Shear Governing, 2) Bending Governing and 3) Combined Shear and Bending

![](_page_21_Figure_1.jpeg)

# Nonlinear AB Structure Displacements for 1) Shear Governing, 2) Bending Governing and 3) Combined Shear and Bending

![](_page_22_Figure_1.jpeg)

### 4. Comparative Nonlinear Results Vs. CSI PERFORM3D Code for Low-Rise Shearwall Auxiliary Building (AB)

![](_page_23_Figure_1.jpeg)

#### Comparative ISRS and ATF Results for 0.60g Input (2x DBE) Node 33 Acceleration Response Spectra Comparison, RGY 0.6g Node 33 Acceleration Transfer Function Comparison, RGY 0.6g

ACS SASSI LINEAR ACS SASSI LINEAR ACS SASSI NONLINEAR ACS SASSI NONLINEAR PERFORM3D Spectra Acceleration Transfer Function Acceleration Response Node 33 Low-Rise Aux Building (AB) **Include Shear Effects Only** ACS SASSI Linear 10 10<sup>0</sup> 10<sup>1</sup> Frequency [45] ration Transfer Function Comparison, RGY 0.3g **ACS SASSI Nonlinear** Frequency [Hz] Node 243 Acceleration Response Spectra Compari ACS SASS PERFORM3D ACS SASSI LINEAR ACS SASS ACS SASSI NONLINEAR PERFORM3D Spectra Acceleration Transfer Function Acceleration Response **Node 243** 0 0.2 10<sup>0</sup> 10<sup>1</sup> 10<sup>1</sup> 10 10<sup>°</sup> 25 Frequency [Hz] Frequency [Hz]

# Comparative Nonlinear Shear Strain in Panel 17 for 0.60g (2xDBE)

Low-Rise Aux Building (AB) Include Shear Effects Only

![](_page_25_Picture_2.jpeg)

![](_page_25_Figure_3.jpeg)

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### 5. Comparative Nonlinear Results Vs. OpenSees Codes for Mid-Rise Shearwall Tower Building (TB)

![](_page_26_Figure_1.jpeg)

TB is a mid-rise building with directional H/L=3.42 and 2.35.

![](_page_26_Figure_3.jpeg)

![](_page_26_Figure_4.jpeg)

![](_page_26_Figure_5.jpeg)

![](_page_26_Figure_6.jpeg)

# **SSI Inputs and RC Wall Section Geometry and Reinforcement**

Seismic Input

RG1.60 Spectrum with 0.70g

Soil Layering

Uniform hard rock (rigid)

![](_page_27_Figure_5.jpeg)

# ISRS for Option NON w/ CM vs. OpenSees RC Structure Codes

![](_page_28_Figure_1.jpeg)

### Nonlinear Displacements for Option NON w/ CM vs. OpenSees

X-Dir

Y-Dir

![](_page_29_Figure_3.jpeg)

# End of Part 1

# Thank you!

# NONLINEAR SEISMIC SSI FOR REINFORCED CONCRETE BUILDINGS IN ACCORDANCE WITH ENGINEERING BEST PRACTICES IN US AND JAPAN

### PART 2: Implementation & Application Based on US and Japan Practices

![](_page_31_Picture_2.jpeg)

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![](_page_31_Picture_6.jpeg)

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# **Part 2 Presentation Content**

- 6. ACS SASSI Option NON Implementation for Nonlinear SSI Analysis
- 7. Comparative TB Nonlinear Results for US and Japan Practices
- 8. Concluding Remarks

# 6. ACS SASSI Opt NON Implementation for Nonlinear SSI Analysis

![](_page_33_Figure_1.jpeg)

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# Steps 1-2: Prepare the 3DFEM with Separate Shell Groups for Walls

#### **Build SSI Model**

Analyst creates a 3DFEM for with element groups for each wall.

> AB\_Model.pre Input File

![](_page_34_Figure_4.jpeg)

Analyst uses UI Section-Cut commands to split 3DFEM model into wall submodels

![](_page_34_Figure_6.jpeg)

Use ACS SASSI UI Section-cut commands to split the 3DFEM model in Wall submodels (Shell Groups).

![](_page_34_Picture_8.jpeg)

The 3DFEM and Wall submodel .pre file are used next to perform automatic section-cuts, section geometry identification for each wall submodel.

# Steps 3-4: Perform SSI Analysis for Gravity and Seismic Loads

![](_page_35_Figure_1.jpeg)

#### Step 3:

#### **Perform SSI analysis (Batch)**

1) Perform seismic ACS SASSI SSI analysis for the 3DFEM model using "Simultaneous Cases" ANALYS option to get FILE8s for post-processing **Step 4**:

#### STRESS post-processing runs (Batch):

2) Run STRESS for the seismic inputs in X, Y and Z directions and create three binary DB for each input direction.

3) Run STRESS for the gravity (static) load for Z direction and create gravity binary DB
Combine Three Seismic STRESS binary BD (UI):
4) Use COMBTHSDB to combine the seismic binary DBs for X, Y and Z in a single binary DB.

The Gravity and Seismic binary DBs are used in Step 5 for automatic section-cut calculations.

# Step 5: Automatic Section Geometry Identification and Section-Cuts at Each Floor Level

![](_page_36_Figure_1.jpeg)

#### Step 5:

Section\_Cut\_for\_BBC Module\_runs (Batch): This module performs automatic section-cuts and identify the section geometries for all floor levels.

#### Output files:

The Section\_Data\_for\_BBC.out output file produced by the run includes section-cut forces and geometry to be reviewed by the user in Step 6.

The *Modelname\_Section\_Data.out* as the general output file with input data and section geometry results.

The *Modelname\_Section\_Data.txt*, *output* file with the section data and other input data for next step

![](_page_37_Figure_0.jpeg)

### Step 6: Analyst Review of Section\_Data Files To Prepare Nonlinear Input

### User Section Review Adding RC Material Inputs

Section Data for BBC.out (Step 5)

**Step 6** *Revised\_Section\_Data\_for\_BBC.in* file

#### Step 6:

Analyst shall edit the Section\_Data\_for\_BBC.out file for checking the automatic generated section-cut geometries (web and effective flanges sizes including floor openings effects). The analyst can modify section parameters based on engineering judgements and need to input concrete and steel nonlinear material parameters. Analyst should save the revised file as *Revised\_Section\_Data\_for\_BBC.in* file. This file is used as an input of Step 7.

Section data are provided in international units (kN and m)

#### Revised\_Section\_Data\_for\_BBC. in (Step 6)

																				<b>۱</b>	
1	5							-			1		5								
2	-8.026	4 0.0	000	16.764							2		-8.0264	0.000	16.764						
3	1										3		1								
4	0.9	49395E+05	0.3	36417E+07	0.153516E+	06					-4		0.9493	95E+05	0.336417E+07	0.153516E4	-06				
5	-3.365	0 7.9	327	1.5240	7.9827	1.5240	24.079	1.5240	5.0674	5.0674	5		-3.3650	7.982	7 1.5240	7.9827	1.5240	24.079	1.5240	5.0674	5.0674
6	0								-		-	_									
7	.000	0 0.0	000	0.0000	0.0000						7		1.1950	1.598	0 1.2460	0.95300					
8	0.2	48546E+08	0.10	6216E+08	0.0000E+00	0.0000E+00	0.00000	DE+00 0.	000000E+00	0.0000E+00	8		0.2485	46E+08	0.330000E+05	0.2000E-02	0.4000E-02	0.205000E+	09 0	.345000E+06	0.1850E-0
9	2										9		2								
10	0.9	64498E+05	0.2	23449E+07	0.193119E+	06					10		0.9644	98E+05	0.223449E+07	0.193119E4	-06				
11	4.748	8 7.9	327	1.5240	7.9827	1.5240	24.079	1.5240	7.3088	7.3088	11		4.7488	7.982	7 1.5240	7.9827	1.5240	24.079	1.5240	7.3088	7.3088
12	0										12		0								
13	.000	0.0	000	0.0000	0.0000						13		1.1950	1.598	0 1.2460	0.95300					
14	0.2	48546E+08	0.1	6216E+08	0.0000E+00	0.0000E+00	0.00000	DE+00 0.	000000E+00	0.0000E+00	14	-	0.2485	46E+08	0.330000E+05	0.2000E-02	0.4000E-02	0.205000E+	09 0	345000E+06	0.1850E-0
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### Section\_Data\_for\_BBC.out File from Section\_Cuts\_for\_BBC Module (Step5)

#### Example for Wall 5 Submodel with 3 Floors (and Sections)

![](_page_39_Figure_2.jpeg)

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# Revised\_Section\_Data\_for\_BBC.in File Data Description

	Line 6: NOPN, X0S, X0I, Z0S, Z0I, X1S, X1I, Z	Z1S, Z1I (Openings explicitly defined)	where							
	NOPEN = Total number of openings of the wall									
X0S, X1S, = Superior X coordinates at the top of each wall panel opening										
	(0I, X1I, = Inferior X coordinates at the bottom of each wall panel opening									
	Z0S, Z1S, = Superior Z coordinates at the top of each wall panel opening									
	Z0I, Z1I, = Inferior Z coordinates at the bo	ttom of each wall panel opening								
	Line 7: PVf1, PVf2, PVw, PHw (Wall Reinforcement Percentage)									
	PVf1 = Reinforcement percentage for Flange 1 (top)									
	PVf2 = Reinforcement percentage for Flange 2	(bottom)								
PVw = Reinforcement percentage for Web (vertical) PHw = Reinforcement percentage for Web (horizontal) Line 8: Ec, Fc, Epsc_y, Epsc_u, Es, Fs, Epss_y, Epss_u										
								Ec = Concrete E modulus		
								Fc = Concrete Fc strength	These are a constant of all he insut	
	Epsc_y = Concrete Yielding strain	I nese are parameters shall be input								
	by analyst for each wall submodel	odel								
Es – Steel E modulus for each floor level cross-section										
	Fs – Steel Fy yielding									
	Epss_y – Steel Yielding strain									
	Epss_u – Steel Ultimate strain									
I										

Repeat line 3 to line 8 for all the sections of the wall.

### Revised\_Section\_Data\_for\_BBC.in Input for BBC\_JEAC\_4601\_2015 Module

**Example for Wall 5 with 3 Floors (and Sections)** 

```
3
-8.0264
         16.764
                  40.843
 0.264106E+05 0.409823E+06 0.404182E+05
4.7488
         14,441
                  1.5240
                                     1.5240
                                             24.079
                                                       1.5240
                                                                13.801
                                                                         13.801
                           14,441
 0
1.1950
         1.5980
                  1.2460
                          0.95300
0.248546E+08 0.3300E+05 0.200E-02 0.400E-02 0.205000E+09 0.3450E+06 0.185E-02 0.500E-01
 2
 0.228232E+05
                0.188437E+06 0.358970E+05
                                                                                      Section data are provided only in
                                                                17.650
11.924
         14,441
                  1.5240
                                     1.5240
                                             24.079
                                                       1.5240
                                                                         17.650
                           14,441
                                                                                      International system (kN and m)
 0
1,1950
         1.5980
                  1 2460
                          0.95300
0.248546E+08 0.3300E+05 0.200E-02 0.400E-02 0.205000E+09 0.3450E+06 0.185E-02 0.500E-01
 3
 0.124042E+05 0.371685E+05 0.215392E+05
19.391
         14,441
                  1.5240
                           14,441
                                     1.5240
                                             24.079
                                                       1.5240
                                                                20,946
                                                                         20.946
 0
1,1950
         1.5980
                  1.2460
                          0.95300
0.248546E+08 0.3300E+05 0.200E-02 0.400E-02
                                                 0.205000E+09
                                                                0.3450E+06 0.185E-02 0.500E-01
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```

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G15 - Panel 23

G30 - Panel 22

G35 – Panel 21

# **Steps 7-8: Computes Shear and Bending BBCs**

![](_page_42_Figure_1.jpeg)

# **Steps 9-10: Nonlinear SSI Analysis and Post-Processing**

![](_page_42_Figure_3.jpeg)

# 7. Comparative TB Nonlinear Results for US and Japan Practices

![](_page_43_Figure_1.jpeg)

![](_page_43_Figure_2.jpeg)

![](_page_43_Figure_3.jpeg)

![](_page_43_Figure_4.jpeg)

# **Computed Effective Flange Width for ACI-318 and JEAC 4601**

	Flange 1	L1C (m)	Flange 2 L2C (m)				
Panel #	JEAC 4601 2015	ACI 318-14	JEAC 4601 2015	ACI 318-14			
1, 6	6.12	3.5	6.12	3.5			
2, 7	7.43	5.5	7.43	5.5			
3, 8	7.87	7.5	7.87	7.5			
4, 9	8.09	8.75	8.09	8.75			
5, 10	8.22	8.75	8.22	8.75			
11, 16	6.42	3.5	6.42	3.5			
12, 17	9.58	5.5	9.58	5.5			
13, 18	10.64	7.5	10.64	7.5			
14, 19	11.16	9.5	11.16	9.5			
15, 20	11.48	10.5	11.48	10.5			

# **Computed Shear BBCs for TB Transverse Walls in X-Dir**

![](_page_45_Figure_1.jpeg)

# **Computed Bending BBCs for TB Transverse Walls in X-Dir**

![](_page_46_Figure_1.jpeg)

### Iterated ATF Response Using Same Hysteretic Models for US and Japan Design Practices

![](_page_47_Figure_1.jpeg)

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# Iterated Walls Stiffness and Damping for 0.70g RG1.60 Input

Using JEAC PO Models and CM Models with **No Damping Limit** (directly FEA nonlinear results)

![](_page_48_Figure_2.jpeg)

### Iterated ATF for JEAC PO Models and CM Models w/ No Damping Limit

![](_page_49_Figure_1.jpeg)

### Iterated ISRS for JEAC PO Models and CM Models w/ No Damping Limit)

![](_page_50_Figure_1.jpeg)

# Iterated Walls Stiffness and Damping for 0.70g RG1.60 Input

Using JEAC PO and CM Models with **Damping < 10%** per ASCE 4 Section 3 Recommendation

![](_page_51_Figure_2.jpeg)

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# Iterated ATF for JEAC PO Models and CM Models with D<10%

![](_page_52_Figure_1.jpeg)

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# Iterated ISRS for JEAC PO Models and CM Models with D<10%

![](_page_53_Figure_1.jpeg)

# Shear Hysteretic Response for JEAC PO and CM with D<10%

![](_page_54_Figure_1.jpeg)

### Nonlinear Displacements for X and Y Dir at Top of TB for JEAC PO Models and ASCE 4 CM with D<10%

![](_page_55_Figure_1.jpeg)

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# **Concluding Remarks**

### A. Remarks on Nonlinear SSI Analysis Procedure Based on Best Practices

Very importantly, the developed nonlinear SSI analysis tool (ACS SASSI Option NON) *maintains the safety margins as accepted by the current standards and regulations*, at the same time providing a large reduction of the nonlinear SSI analysis costs in comparison with the existing, more sophisticated nonlinear FEA codes in the time domain.

We believe that such a *practical engineering analysis tool* is highly needed for nuclear industry.

### B. Remarks on Nonlinear Results Based on US and Japan Design Practices

- 1. The comparative study results show that if the Japanese and US standard recommendations for hysteretic damping limitation are respected, then, the computed nonlinear ISRS amplitudes are close.
- 2. The JEAC PO hysteretic models have much lower hysteretic damping (PO shear model has no damping and PODT bending has between 0 and 15%) which amplifies seismic responses and produces a shift of the structural dominant frequencies to lower frequencies. As a result of the lower damping, the structural displacements are significantly larger for the JEAC PO models.
- 3. Using directly the nonlinear FEA code results (similar with using the CM models with no damping limit) could produce much lower nonlinear SSI responses than those computed by respecting the Japanese or US standard recommendations, especially due to the lack of hysteretic damping limitation.

*WARNING:* Using directly the nonlinear FEA code results without checking the compliance with regulatory requirements could significantly lower the nonlinear responses. By this may produce much lower seismic safety margins that those corresponding to the existing design regulation requirements. Nuclear industry analysts should understand and pay attention to these serious methodology risks.

# References

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# End of Part 2

# Thank you!